

## Lecture 8: Conditional expectation

Conditional probability  $P(B|A) = P(A \cap B)/P(A)$  for events  $A$  and  $B$  with  $P(A) > 0$   
 $P(X \in B|Y \in A)$   
 $P(X \in B|Y = y)$ ?

**Definition 1.6.** Let  $X$  be an integrable random variable on  $(\Omega, \mathcal{F}, P)$ .

(i) Let  $\mathcal{A}$  be a sub- $\sigma$ -field of  $\mathcal{F}$ . The *conditional expectation* of  $X$  given  $\mathcal{A}$ , denoted by  $E(X|\mathcal{A})$ , is the a.s.-unique random variable satisfying the following two conditions:

- (a)  $E(X|\mathcal{A})$  is measurable from  $(\Omega, \mathcal{A})$  to  $(\mathcal{R}, \mathcal{B})$ ;
- (b)  $\int_A E(X|\mathcal{A})dP = \int_A XdP$  for any  $A \in \mathcal{A}$ .

(Note that the existence of  $E(X|\mathcal{A})$  follows from Theorem 1.4.)

(ii) Let  $B \in \mathcal{F}$ . The *conditional probability* of  $B$  given  $\mathcal{A}$  is defined to be  $P(B|\mathcal{A}) = E(I_B|\mathcal{A})$ .

(iii) Let  $Y$  be measurable from  $(\Omega, \mathcal{F}, P)$  to  $(\Lambda, \mathcal{G})$ . The conditional expectation of  $X$  given  $Y$  is defined to be  $E(X|Y) = E[X|\sigma(Y)]$ .

$\sigma(Y)$  contains “the information in  $Y$ ”

$E(X|Y)$  is the “expectation” of  $X$  given the information provided by  $Y$

**Lemma 1.2.** Let  $Y$  be measurable from  $(\Omega, \mathcal{F})$  to  $(\Lambda, \mathcal{G})$  and  $Z$  a function from  $(\Omega, \mathcal{F})$  to  $\mathcal{R}^k$ . Then  $Z$  is measurable from  $(\Omega, \sigma(Y))$  to  $(\mathcal{R}^k, \mathcal{B}^k)$  if and only if there is a measurable function  $h$  from  $(\Lambda, \mathcal{G})$  to  $(\mathcal{R}^k, \mathcal{B}^k)$  such that  $Z = h \circ Y$ .

The function  $h$  in  $E(X|Y) = h \circ Y$  is a Borel function on  $(\Lambda, \mathcal{G})$ .

Let  $y \in \Lambda$ . We define

$$E(X|Y = y) = h(y)$$

to be the conditional expectation of  $X$  given  $Y = y$ .

Note that  $h(y)$  is a function on  $\Lambda$ , whereas  $h \circ Y = E(X|Y)$  is a function on  $\Omega$ .

For a random vector  $X$ ,  $E(X|\mathcal{A})$  is defined as the vector of conditional expectations of components of  $X$ .

**Example 1.21.** Let  $X$  be an integrable random variable on  $(\Omega, \mathcal{F}, P)$ ,  $A_1, A_2, \dots$  be disjoint events on  $(\Omega, \mathcal{F}, P)$  such that  $\cup A_i = \Omega$  and  $P(A_i) > 0$  for all  $i$ , and let  $a_1, a_2, \dots$  be distinct real numbers. Define  $Y = a_1 I_{A_1} + a_2 I_{A_2} + \dots$ . We now show that

$$E(X|Y) = \sum_{i=1}^{\infty} \frac{\int_{A_i} XdP}{P(A_i)} I_{A_i}.$$

We need to verify (a) and (b) in Definition 1.6 with  $\mathcal{A} = \sigma(Y)$ .

Since  $\sigma(Y) = \sigma(\{A_1, A_2, \dots\})$ , it is clear that the function on the right-hand side is measurable on  $(\Omega, \sigma(Y))$ .

For any  $B \in \mathcal{B}$ ,  $Y^{-1}(B) = \cup_{i:a_i \in B} A_i$ . Using properties of integrals, we obtain that

$$\begin{aligned}
\int_{Y^{-1}(B)} X dP &= \sum_{i: a_i \in B} \int_{A_i} X dP \\
&= \sum_{i=1}^{\infty} \frac{\int_{A_i} X dP}{P(A_i)} P(A_i \cap Y^{-1}(B)) \\
&= \int_{Y^{-1}(B)} \left[ \sum_{i=1}^{\infty} \frac{\int_{A_i} X dP}{P(A_i)} I_{A_i} \right] dP.
\end{aligned}$$

This verifies (b) and thus the result.

Let  $h$  be a Borel function on  $\mathcal{R}$  satisfying  $h(a_i) = \int_{A_i} X dP / P(A_i)$ .

Then  $E(X|Y) = h \circ Y$  and  $E(X|Y = y) = h(y)$ .

**Proposition 1.9.** Let  $X$  be a random  $n$ -vector and  $Y$  a random  $m$ -vector. Suppose that  $(X, Y)$  has a joint p.d.f.  $f(x, y)$  w.r.t.  $\nu \times \lambda$ , where  $\nu$  and  $\lambda$  are  $\sigma$ -finite measures on  $(\mathcal{R}^n, \mathcal{B}^n)$  and  $(\mathcal{R}^m, \mathcal{B}^m)$ , respectively. Let  $g(x, y)$  be a Borel function on  $\mathcal{R}^{n+m}$  for which  $E|g(X, Y)| < \infty$ . Then

$$E[g(X, Y)|Y] = \frac{\int g(x, Y) f(x, Y) d\nu(x)}{\int f(x, Y) d\nu(x)} \quad \text{a.s.}$$

**Proof.** Denote the right-hand side by  $h(Y)$ . By Fubini's theorem,  $h$  is Borel. Then, by Lemma 1.2,  $h(Y)$  is Borel on  $(\Omega, \sigma(Y))$ . Also, by Fubini's theorem,  $f_Y(y) = \int f(x, y) d\nu(x)$  is the p.d.f. of  $Y$  w.r.t.  $\lambda$ . For  $B \in \mathcal{B}^m$ ,

$$\begin{aligned}
\int_{Y^{-1}(B)} h(Y) dP &= \int_B h(y) dP_Y \\
&= \int_B \frac{\int g(x, y) f(x, y) d\nu(x)}{\int f(x, y) d\nu(x)} f_Y(y) d\lambda(y) \\
&= \int_{\mathcal{R}^n \times B} g(x, y) f(x, y) d\nu \times \lambda \\
&= \int_{\mathcal{R}^n \times B} g(x, y) dP_{(X, Y)} \\
&= \int_{Y^{-1}(B)} g(X, Y) dP,
\end{aligned}$$

where the first and the last equalities follow from Theorem 1.2, the second and the next to last equalities follow from the definition of  $h$  and p.d.f.'s, and the third equality follows from Theorem 1.3 (Fubini's theorem).

$(X, Y)$ : a random vector with a joint p.d.f.  $f(x, y)$  w.r.t.  $\nu \times \lambda$

The *conditional* p.d.f. of  $X$  given  $Y = y$ :  $f_{X|Y}(x|y) = f(x, y) / f_Y(y)$

$f_Y(y) = \int f(x, y) d\nu(x)$  is the marginal p.d.f. of  $Y$  w.r.t.  $\lambda$ .

For each fixed  $y$  with  $f_Y(y) > 0$ ,  $f_{X|Y}(x|y)$  is a p.d.f. w.r.t.  $\nu$ .

Then Proposition 1.9 states that

$$E[g(X, Y)|Y] = \int g(x, Y) f_{X|Y}(x|Y) d\nu(x)$$

i.e., the conditional expectation of  $g(X, Y)$  given  $Y$  is equal to the expectation of  $g(X, Y)$  w.r.t. the conditional p.d.f. of  $X$  given  $Y$ .

Properties

**Proposition 1.10.** Let  $X, Y, X_1, X_2, \dots$  be integrable random variables on  $(\Omega, \mathcal{F}, P)$  and  $\mathcal{A}$  be a sub- $\sigma$ -field of  $\mathcal{F}$ .

- (i) If  $X = c$  a.s.,  $c \in \mathcal{R}$ , then  $E(X|\mathcal{A}) = c$  a.s.
- (ii) If  $X \leq Y$  a.s., then  $E(X|\mathcal{A}) \leq E(Y|\mathcal{A})$  a.s.
- (iii) If  $a \in \mathcal{R}$  and  $b \in \mathcal{R}$ , then  $E(aX + bY|\mathcal{A}) = aE(X|\mathcal{A}) + bE(Y|\mathcal{A})$  a.s.
- (iv)  $E[E(X|\mathcal{A})] = EX$ .
- (v)  $E[E(X|\mathcal{A})|\mathcal{A}_0] = E(X|\mathcal{A}_0) = E[E(X|\mathcal{A}_0)|\mathcal{A}]$  a.s., where  $\mathcal{A}_0$  is a sub- $\sigma$ -field of  $\mathcal{A}$ .
- (vi) If  $\sigma(Y) \subset \mathcal{A}$  and  $E|XY| < \infty$ , then  $E(XY|\mathcal{A}) = YE(X|\mathcal{A})$  a.s.
- (vii) If  $X$  and  $Y$  are independent and  $E|g(X, Y)| < \infty$  for a Borel function  $g$ , then  $E[g(X, Y)|Y = y] = E[g(X, y)]$  a.s.  $P_Y$ .
- (viii) If  $EX^2 < \infty$ , then  $[E(X|\mathcal{A})]^2 \leq E(X^2|\mathcal{A})$  a.s.
- (ix) (Fatou's lemma). If  $X_n \geq 0$  for any  $n$ , then  $E(\liminf_n X_n|\mathcal{A}) \leq \liminf_n E(X_n|\mathcal{A})$  a.s.
- (x) (Dominated convergence theorem). Suppose that  $|X_n| \leq Y$  for any  $n$  and  $X_n \rightarrow_{a.s.} X$ . Then  $E(X_n|\mathcal{A}) \rightarrow_{a.s.} E(X|\mathcal{A})$ .

**Example 1.22.** Let  $X$  be a random variable on  $(\Omega, \mathcal{F}, P)$  with  $EX^2 < \infty$  and let  $Y$  be a measurable function from  $(\Omega, \mathcal{F}, P)$  to  $(\Lambda, \mathcal{G})$ . One may wish to predict the value of  $X$  based on an observed value of  $Y$ . Let  $g(Y)$  be a predictor, i.e.,  $g \in \mathfrak{N} = \{\text{all Borel functions } g \text{ with } E[g(Y)]^2 < \infty\}$ . Each predictor is assessed by the “mean squared prediction error”  $E[X - g(Y)]^2$ . We now show that  $E(X|Y)$  is the best predictor of  $X$  in the sense that

$$E[X - E(X|Y)]^2 = \min_{g \in \mathfrak{N}} E[X - g(Y)]^2.$$

First, Proposition 1.10(viii) implies  $E(X|Y) \in \mathfrak{N}$ . Next, for any  $g \in \mathfrak{N}$ ,

$$\begin{aligned} E[X - g(Y)]^2 &= E[X - E(X|Y) + E(X|Y) - g(Y)]^2 \\ &= E[X - E(X|Y)]^2 + E[E(X|Y) - g(Y)]^2 \\ &\quad + 2E\{[X - E(X|Y)][E(X|Y) - g(Y)]\} \\ &= E[X - E(X|Y)]^2 + E[E(X|Y) - g(Y)]^2 \\ &\quad + 2E\{E\{[X - E(X|Y)][E(X|Y) - g(Y)]|Y\}\} \\ &= E[X - E(X|Y)]^2 + E[E(X|Y) - g(Y)]^2 \\ &\quad + 2E\{[E(X|Y) - g(Y)]E[X - E(X|Y)|Y]\} \\ &= E[X - E(X|Y)]^2 + E[E(X|Y) - g(Y)]^2 \\ &\geq E[X - E(X|Y)]^2, \end{aligned}$$

where the third equality follows from Proposition 1.10(iv), the fourth equality follows from Proposition 1.10(vi), and the last equality follows from Proposition 1.10(i), (iii), and (vi).