

Lecture 22: Weighted LSE and linear mixed effects models

The weighted LSE

In the linear model

$$X = Z\beta + \varepsilon, \quad (1)$$

the unbiased LSE of $I^r\beta$ may be improved by a slightly biased estimator when $V = \text{Var}(\varepsilon)$ is not $\sigma^2 I_n$ and the LSE is not BLUE.

Assume that Z is of full rank so that every $I^r\beta$ is estimable.

If V is known, then the BLUE of $I^r\beta$ is $I^r\check{\beta}$, where

$$\check{\beta} = (Z^T V^{-1} Z)^{-1} Z^T V^{-1} X \quad (2)$$

(see the discussion after the statement of assumption A3 in §3.3.1).

If V is unknown and \hat{V} is an estimator of V , then an application of the substitution principle leads to a *weighted least squares estimator*

$$\hat{\beta}_w = (Z^T \hat{V}^{-1} Z)^{-1} Z^T \hat{V}^{-1} X. \quad (3)$$

The weighted LSE is not linear in X and not necessarily unbiased for β .

If the weighted LSE $I^\tau \widehat{\beta}_w$ is unbiased, then the LSE $I^\tau \widehat{\beta}$ may not be a BLUE, since $\text{Var}(I^\tau \widehat{\beta}_w)$ may be smaller than $\text{Var}(I^\tau \widehat{\beta})$.

Asymptotic properties of the weighted LSE depend on the asymptotic behavior of \widehat{V} .

We say that \widehat{V} is consistent for V iff

$$\|\widehat{V}^{-1} V - I_n\|_{\max} \rightarrow_p 0, \quad (4)$$

where $\|A\|_{\max} = \max_{i,j} |a_{ij}|$ for a matrix A whose (i,j) th element is a_{ij} .

Theorem 3.17

Consider model (1) with a full rank Z . Let $\check{\beta}$ and $\widehat{\beta}_w$ be defined by (2) and (3), respectively, with a \widehat{V} consistent in the sense of (4).

Under the conditions in Theorem 3.12,

$$I^\tau (\widehat{\beta}_w - \beta) / a_n \rightarrow_d N(0, 1),$$

where $l \in \mathcal{R}^p$, $l \neq 0$, and

$$a_n^2 = \text{Var}(I^\tau \check{\beta}) = I^\tau (Z^\tau V^{-1} Z)^{-1} l.$$

Proof

Using the same argument as in the proof of Theorem 3.12, we obtain that

$$I^\tau(\check{\beta} - \beta)/a_n \rightarrow_d N(0, 1).$$

By Slutsky's theorem, the result follows from

$$I^\tau \hat{\beta}_w - I^\tau \check{\beta} = o_p(a_n).$$

Define

$$\xi_n = I^\tau (Z^\tau \hat{V}^{-1} Z)^{-1} Z^\tau (\hat{V}^{-1} - V^{-1}) \varepsilon$$

and

$$\zeta_n = I^\tau [(Z^\tau \hat{V}^{-1} Z)^{-1} - (Z^\tau V^{-1} Z)^{-1}] Z^\tau V^{-1} \varepsilon.$$

Then

$$I^\tau \hat{\beta}_w - I^\tau \check{\beta} = \xi_n + \zeta_n.$$

The result follows from $\xi_n = o_p(a_n)$ and $\zeta_n = o_p(a_n)$ (details are in the textbook).

- Theorem 3.17 shows that as long as \widehat{V} is consistent in the sense of (4), the weighted LSE $\widehat{\beta}_w$ is asymptotically as efficient as $\check{\beta}$, which is the BLUE if V is known.
- By Theorems 3.12 and 3.17, the asymptotic relative efficiency of the LSE $I^\tau \widehat{\beta}$ w.r.t. the weighted LSE $I^\tau \widehat{\beta}_w$ is

$$\frac{I^\tau (Z^\tau V^{-1} Z)^{-1} I}{I^\tau (Z^\tau Z)^{-1} Z^\tau V Z (Z^\tau Z)^{-1} I},$$

which is always less than 1 and equals 1 if $I^\tau \widehat{\beta}$ is a BLUE ($\widehat{\beta} = \check{\beta}$).

- Finding a consistent \widehat{V} is possible when V has a certain type of structure.

Example 3.29

Consider model (1).

Suppose that $V = \text{Var}(\varepsilon)$ is a block diagonal matrix with the i th diagonal block

$$\sigma^2 I_{m_i} + U_i \Sigma U_i^\tau, \quad i = 1, \dots, k, \quad (5)$$

where m_i 's are integers bounded by a fixed integer m , $\sigma^2 > 0$ is an unknown parameter, Σ is a $q \times q$ unknown nonnegative definite matrix,

U_i is an $m_i \times q$ full rank matrix whose columns are in $\mathcal{R}(W_i)$, $q < \inf_i m_i$, and W_i is the $p \times m_i$ matrix such that $Z^\tau = (W_1 \ W_2 \ \dots \ W_k)$. Under (5), a consistent \hat{V} can be obtained if we can obtain consistent estimators of σ^2 and Σ .

Let $X = (Y_1, \dots, Y_k)$, where Y_i is an m_i -vector, and let R_i be the matrix whose columns are linearly independent rows of W_i .

If Y_i 's are independent and $\sup_i E|\varepsilon_i|^{2+\delta} < \infty$ for some $\delta > 0$, then

$$\hat{\sigma}^2 = \frac{1}{n - kq} \sum_{i=1}^k Y_i^\tau [I_{m_i} - R_i(R_i^\tau R_i)^{-1} R_i^\tau] Y_i$$

is an unbiased and consistent estimator of σ^2 .

Let $r_i = Y_i - W_i^\tau \hat{\beta}$ and

$$\hat{\Sigma} = \frac{1}{k} \sum_{i=1}^k \left[(U_i^\tau U_i)^{-1} U_i^\tau r_i r_i^\tau U_i (U_i^\tau U_i)^{-1} - \hat{\sigma}^2 (U_i^\tau U_i)^{-1} \right].$$

It can be shown (exercise) that $\hat{\Sigma}$ is consistent for Σ in the sense that $\|\hat{\Sigma} - \Sigma\|_{\max} \rightarrow_p 0$ or, equivalently, $\|\hat{\Sigma} - \Sigma\| \rightarrow_p 0$ (see Exercise 116).

Linear mixed effects models

Adding random effects to a linear model

Consider linear model (1), $X = Z\beta + \varepsilon$.

In many applications we need to add random-effect terms, which leads to the linear mixed effects model

$$X = Z\beta + U_1\xi_1 + \cdots + U_k\xi_k + \varepsilon \quad (6)$$

where U_j 's are fixed matrices and ξ_1, \dots, ξ_k are independent unobserved random effects (vectors), and ε and ξ_j 's are independent.

The following are two main reasons for adding random effects.

- We want to model the correlation among the errors, since $U_1\xi_1 + \cdots + U_k\xi_k + \varepsilon$ can be viewed as error in a linear model.
- Random effects present unobserved variables of interests.

It is typically assumed that ξ_j 's and ε have mean 0 and finite covariance matrices and $\text{Var}(\varepsilon) = \sigma^2 I_n$ so that

$$E(X) = Z\beta \quad \text{and} \quad \text{Var}(X) = U_1 \text{Var}(\xi_1) U_1^T + \cdots + U_k \text{Var}(\xi_k) U_k^T + \sigma^2 I_n$$

A special case is that $\text{Var}(\xi_j) = \sigma_j^2 I_{m_j}$, where m_j is the dimension of ξ_j , $j = 1, \dots, k$, in which case $\sigma_1^2, \dots, \sigma_k^2$ are called variance components so that model (6) is also called variance components models.

Example: One-way random effects model

The one-way random effect model

$$Y_{ij} = \mu + A_i + e_{ij}, \quad j = 1, \dots, n_i, \quad i = 1, \dots, m,$$

discussed previously is a special case of model (6), $\xi_1 = (A_1, \dots, A_m)$, $Z = J_n$, and U_1 is block diagonal whose i th diagonal block is J_{n_i} .

Parameter estimation

Besides β , parameters of interests in a linear mixed effects model are $\Sigma_j = \text{Var}(\xi_j)$, $j = 1, \dots, k$, and σ^2 .

We carry out the estimation in two steps.

- 1 Obtain estimators $\hat{\Sigma}_1, \dots, \hat{\Sigma}_k$, and $\hat{\sigma}^2$.
- 2 Let $\Sigma = \text{Var}(X)$ and $\hat{\Sigma} = U_1 \hat{\Sigma}_1 U_1^\tau + \dots + U_k \hat{\Sigma}_k U_k^\tau + \hat{\sigma}^2 I_n$.

We then estimate β by the weighted LSE

$$\hat{\beta}_W = (Z^\tau \hat{\Sigma}^{-1} Z)^{-1} Z^\tau \hat{\Sigma}^{-1} X$$

Main approaches for estimating variance components

- 1 The ANOVA method.
- 2 The MINQUE (developed by C.R. Rao)
- 3 The maximum likelihood estimation.
- 4 The restricted maximum likelihood estimation.

Three steps in estimating variance components

We consider the ANOVA method and the special case where $\Sigma_i = \sigma_i^2 I_{m_i}$, $i = 1, \dots, k$.

- (1) Treat ξ_i 's as fixed effects and apply the ANOVA technique to obtain sums of squares.
- (2) Treat ξ_i 's as random and derive the expectations of the sums of squares, which are linear functions of variance components.
- (3) Set each sum of squares equal to its expectation, and then follow the method of moments to estimate variance components.

To achieve (1), we need to get the decomposition

$$X^T X = SS_{\beta} + SS_{\xi_1} + \dots + SS_{\xi_k} + SS_{\varepsilon}$$

Deriving sums of squares

To obtain SS_β , we consider model $X = Z\beta + \varepsilon$ and the sum of squares due to regression:

$$SS_\beta = RSS(\beta) = X^\tau Z(Z^\tau Z)^{-1} Z^\tau X$$

To obtain SS_{ξ_1} , we treat ξ_1 as fixed effect in the linear model after removing the β effect, i.e., consider model $X - Z\beta = U_1\xi_1 + \varepsilon$ and the sum of squares due to regression, which is equal to the SS due to regression in model $X = Z\beta + U_1\xi_1 + \varepsilon$ minus the SS due to regression in model $X = Z\beta + \varepsilon$, i.e.,

$$SS_{\xi_1} = RSS(\beta, \xi_1) - RSS(\beta)$$

Similarly, the SS due to regression in model $X = Z\beta + U_1\xi_1 + U_2\xi_2 + \varepsilon$ minus the SS due to regression in model $X = Z\beta + U_1\xi_1 + \varepsilon$ gives

$$SS_{\xi_2} = RSS(\beta, \xi_1, \xi_2) - RSS(\beta, \xi_1)$$

.....

$$SS_{\xi_k} = RSS(\beta, \xi_1, \dots, \xi_k) - RSS(\beta, \xi_1, \dots, \xi_{k-1})$$

Finally,

$$SS_\varepsilon = X^\tau X - RSS(\beta, \xi_1, \dots, \xi_k)$$

For a square matrix M , M^- is its generalized inverse if $M = MM^-M$. To derive a form for SS_{ξ_1} , we use the following result:

$$\begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix}^- = \begin{pmatrix} A_{11}^{-1} + A_{11}^{-1}A_{12}B^-A_{21}A_{11}^{-1} & -A_{11}^{-1}A_{12}B^- \\ -B^-A_{21}A_{11}^{-1} & B^- \end{pmatrix}$$

where $B = A_{22} - A_{21}A_{11}^{-1}A_{12}$.

Under model $X = Z\beta + U_1\xi_1 + \varepsilon$,

$$RSS(\beta, \xi_1) = X^T(Z \ U_1) \begin{pmatrix} Z^T Z & Z^T U_1 \\ U_1^T Z & U_1^T U_1 \end{pmatrix}^- \begin{pmatrix} Z^T \\ U_1^T \end{pmatrix} X$$

Letting $H_Z = Z(Z^T Z)^{-1}Z^T$, $D = I - H_Z$, $B = U_1^T D U_1$, and applying the generalized inverse formula, we obtain that

$$\begin{aligned} RSS(\beta, \xi_1) &= X^T [H_Z + H_Z U_1 B^- U_1^T H_Z - H_Z U_1 B^- U_1^T \\ &\quad - U_1 B^- U_1^T H_Z + U_1 B^- U_1^T] X \\ &= RSS(\beta) + X^T D U_1 B^- U_1^T D X \end{aligned}$$

Hence

$$SS_{\xi_1} = X^T D U_1 (U_1^T D U_1)^- U_1^T D X = X^T (D - D_1) X$$

where $D_1 = D - D U_1 (U_1^T D U_1)^- U_1^T D$

Similarly, we can obtain

$$SS_{\xi_2} = X^\tau (D_1 - D_2)X, \quad D_2 = D_1 - D_1 U_2 (U_2^\tau D_1 U_2)^{-1} U_2^\tau D_1$$

.....

$$SS_{\xi_k} = X^\tau (D_{k-1} - D_k)X, \quad D_k = D_{k-1} - D_{k-1} U_k (U_k^\tau D_{k-1} U_k)^{-1} U_k^\tau D_{k-1}$$

Furthermore, $SS_\varepsilon = X^\tau D_k X$ so that

$$X^\tau X = SS_\beta + SS_{\xi_1} + \cdots + SS_{\xi_k} + SS_\varepsilon$$

Expectations of SS

To derive the expectation of SS_{ξ_i} , we use the following result.

Lemma. For a random vector $X \in \mathcal{R}^n$, if $E(X) = \mu$, $\text{Var}(X) = \Sigma$, and A is an $n \times n$ symmetric matrix, then

$$E(X^\tau A X) = \mu^\tau A \mu + \text{tr}(A \Sigma)$$

For SS_{ξ_1} , since $DZ = D_1 Z = 0$,

$$\begin{aligned} E(SS_{\xi_1}) &= E[X^\tau (D - D_1)X] \\ &= \beta^\tau Z^\tau (D - D_1)Z\beta + \text{tr}[(D - D_1)\text{Var}(X)] \\ &= \text{tr}[(D - D_1)(U_1 \text{Var}(\xi_1)U_1^\tau + \cdots + U_k \text{Var}(\xi_k)U_k^\tau) + \sigma^2 I_n] \end{aligned}$$

Since $\Sigma_i = \sigma_i^2 I_{m_i}$, $i = 1, \dots, k$,

$$\begin{aligned} E(SS_{\xi_1}) &= \text{tr}[(D - D_1)(\sigma_1^2 U_1 U_1^\tau + \dots + \sigma_k^2 U_k U_k^\tau) + \sigma^2 I_n] \\ &= \sigma_1^2 \text{tr}[(D - D_1)U_1 U_1^\tau] + \dots + \sigma_k^2 \text{tr}[(D - D_1)U_k U_k^\tau] + \sigma^2 \text{tr}(D - D_1) \end{aligned}$$

Note that

$$\text{tr}(D - D_1) = \text{tr}[DU_1(U_1^\tau DU_1)^- U_1^\tau D] = \text{rank}(U_1^\tau DU_1) = r_1$$

$$U_1^\tau D_1 U_1 = U_1^\tau DU_1 - U_1^\tau DU_1 (U_1^\tau DU_1)^- U_1^\tau DU_1 = U_1^\tau DU_1 - U_1^\tau DU_1 = 0$$

Hence

$$\begin{aligned} E(SS_{\xi_1}) &= \sigma_1^2 \text{tr}(U_1^\tau DU_1) + \sigma_2^2 [\text{tr}(U_2^\tau DU_2) - \text{tr}(U_2^\tau D_1 U_2)] + \dots \\ &\quad \dots + \sigma_k^2 [\text{tr}(U_k^\tau DU_k) - \text{tr}(U_k^\tau D_1 U_k)] + r_1 \sigma^2 \end{aligned}$$

which is a linear function of variance components.

Since $D_i Z = 0$ and $D_i U_j = 0$, $i = 2, \dots, k$, $i \geq j$, for $i = 2, \dots, k$,

$$\begin{aligned} E(SS_{\xi_j}) &= \text{tr}[(D_{i-1} - D_i)(\sigma_i^2 U_i U_i^\tau + \dots + \sigma_k^2 U_k U_k^\tau) + \sigma^2 I_n] \\ &= \sigma_i^2 \text{tr}(U_i^\tau D_{i-1} U_i) + \sigma_{i+1}^2 [\text{tr}(U_{i+1}^\tau D_{i-1} U_{i+1}) - \text{tr}(U_{i+1}^\tau D_i U_{i+1})] + \\ &\quad \dots + \sigma_k^2 [\text{tr}(U_k^\tau D_{i-1} U_k) - \text{tr}(U_k^\tau D_i U_k)] + r_i \sigma^2 \end{aligned}$$

$$E(SS_\varepsilon) = E(X^\tau D_k X) = \sigma^2 \text{tr}(D_k) = (n - p - r_1 - \dots - r_k) \sigma^2$$

where $r_i = \text{rank}(D_{i-1} - D_i) = \text{rank}(Z, U_1, \dots, U_i) - \text{rank}(Z, U_1, \dots, U_{i-1})$.

Estimation of variance components by ANOVA

Set

$$SS_{\xi_i} = \sigma_i^2 \text{tr}(U_i^\tau D_{i-1} U_i) + \sigma_{i+1}^2 [\text{tr}(U_{i+1}^\tau D_{i-1} U_{i+1}) - \text{tr}(U_{i+1}^\tau D_i U_{i+1})] + \dots + \sigma_k^2 [\text{tr}(U_k^\tau D_{i-1} U_k) - \text{tr}(U_k^\tau D_i U_k)] + r_i \sigma^2$$

$i = 1, \dots, k$

$$SS_\varepsilon = (n - p - r_1 - \dots - r_k) \sigma^2$$

These equations can be easily solved by first obtaining

$$\hat{\sigma}^2 = \frac{SS_\varepsilon}{n - p - r_1 - \dots - r_k}$$

then $\hat{\sigma}_k^2$, then $\hat{\sigma}_{k-1}^2$, ..., then $\hat{\sigma}_1^2$.

- Advantage: estimators can be easily computed and are unbiased.
- Disadvantage: except for $\hat{\sigma}^2$, each $\hat{\sigma}_i^2$ may be negative.

Example: one-way random effects model

The one-way random effects model is

$$X_{ij} = \mu + A_i + e_{ij}, \quad j = 1, \dots, n_i, \quad i = 1, \dots, m,$$

where $\mu \in \mathcal{R}$ is an unknown parameter, A_i 's are iid unobserved random variables having mean 0 and variance $\sigma_1^2 = \sigma_a^2$, e_{ij} 's are iid unobserved random errors with mean 0 and variance σ^2 , and A_i 's and e_{ij} 's are independent.

This is a special case of (6) with $k = 1$, X and ε being vectors of X_{ij} 's and e_{ij} 's, $Z = J_n$, $n = n_1 + \dots + n_m$, U_1 being the block diagonal matrix whose i th block is J_{n_i} , $i = 1, \dots, m$, $\xi_1 = (A_1, \dots, A_m)$, $\rho = 1$, and $\beta = \mu$. It is easy to see that $RSS(\beta) = n^{-1} \bar{X}^2$, where \bar{X} is the mean of all X_{ij} 's.

It can be shown that

$$SS_\varepsilon = \sum_{i=1}^m \sum_{j=1}^{n_i} (X_{ij} - \bar{X}_i)^2, \quad SS_{\xi_1} = \sum_{i=1}^m n_i (\bar{X}_i - \bar{X})^2, \quad \bar{X}_i = \frac{1}{n_i} \sum_{j=1}^{n_i} X_{ij}$$

Also, the matrix $(Z, U_1) = (J_n, U_1)$ has rank m , so $r_1 = m - 1$, and

$$U_1^c D U_1 = U_1^c [I_n - J_n (J_n^c J_n)^{-1} J_n^c] U_1$$

$$\begin{aligned}
&= U_1^\tau U_1 - n^{-1} U_1^\tau J_n J_n^\tau U_1 \\
&= \begin{pmatrix} n_1 & & \\ & \ddots & \\ & & n_m \end{pmatrix} - n^{-1} \begin{pmatrix} n_1 \\ \vdots \\ n_m \end{pmatrix} (n_1 \cdots n_m)
\end{aligned}$$

Hence, $q = \text{tr}(U_1^\tau D U_1) = n - (n_1^2 + \cdots + n_m^2)/n$ and

$$\hat{\sigma}^2 = (n - m)^{-1} SS_\varepsilon, \quad \hat{\sigma}_a^2 = [SS_{\xi_1} - (m - 1)\hat{\sigma}^2]/q$$

In this example, let's find out what the estimator of $\beta = \mu$ is.

First, we find $\hat{\mu}_{V^{-1}} = (J_n^\tau V^{-1} J_n)^{-1} J_n^\tau V^{-1} X$ with $V = \sigma_a^2 U_1 U_1^\tau + \sigma^2 I_n$.

V is a block diagonal matrix with the i th diagonal block $\sigma^2 I_{n_i} + \sigma_a^2 J_{n_i} J_{n_i}^\tau$.

Using the formula

$$(A + BB^\tau)^{-1} = A^{-1} - A^{-1} B (I + B^\tau A^{-1} B)^{-1} B^\tau A^{-1}$$

we obtain that each block has the inverse

$$\left(\sigma^2 I_{n_i} + \sigma_a^2 J_{n_i} J_{n_i}^\tau \right)^{-1} = \frac{1}{\sigma^2} I_{n_i} - \frac{\sigma_a^2}{\sigma^2(\sigma^2 + n_i \sigma_a^2)} J_{n_i} J_{n_i}^\tau$$

Then, V^{-1} is the block diagonal matrix whose i th block diagonal is given by the previous expression, and

$$\begin{aligned}
 J_n^\tau V^{-1} J_n &= \sum_{i=1}^m J_{n_i}^\tau \left[\frac{1}{\sigma^2} I_{n_i} - \frac{\sigma_a^2}{\sigma^2(\sigma^2 + n_i \sigma_a^2)} J_{n_i} J_{n_i}^\tau \right] J_{n_i} \\
 &= \left(\frac{n}{\sigma^2} - \frac{\sigma_a^2}{\sigma^2} \sum_{i=1}^m \frac{n_i^2}{\sigma^2 + n_i \sigma_a^2} \right) = \sum_{i=1}^m \frac{n_i}{\sigma^2 + n_i \sigma_a^2}
 \end{aligned}$$

Writing $X_i = (X_{i1}, \dots, X_{in_i})$, we obtain

$$\begin{aligned}
 J_n^\tau V^{-1} X &= \sum_{i=1}^m J_{n_i}^\tau \left[\frac{1}{\sigma^2} I_{n_i} - \frac{\sigma_a^2}{\sigma^2(\sigma^2 + n_i \sigma_a^2)} J_{n_i} J_{n_i}^\tau \right] X_i \\
 &= \left(\frac{n\bar{X}}{\sigma^2} - \frac{\sigma_a^2}{\sigma^2} \sum_{i=1}^m \frac{n_i^2 \bar{X}_i}{\sigma^2 + n_i \sigma_a^2} \right) = \sum_{i=1}^m \frac{n_i \bar{X}_i}{\sigma^2 + n_i \sigma_a^2}
 \end{aligned}$$

Thus, the WLSE of μ is

$$\begin{aligned}
 \hat{\mu}_W &= (J_n^\tau V^{-1} J_n)^{-1} J_n^\tau V^{-1} X \quad \sigma^2 = \hat{\sigma}^2, \sigma_a^2 = \hat{\sigma}_a^2 \\
 &= \left(\sum_{i=1}^m \frac{n_i \bar{X}_i}{\hat{\sigma}^2 + n_i \hat{\sigma}_a^2} \right) / \left(\sum_{i=1}^m \frac{n_i}{\hat{\sigma}^2 + n_i \hat{\sigma}_a^2} \right)
 \end{aligned}$$

Asymptotic normality of the WLSE $\hat{\mu}_W$, $\hat{\sigma}^2$ and $\hat{\sigma}_a^2$ can be proved.