

Discussion 2

• Bayesian Model

- the prior $\pi(\theta)$ for θ .
- the conditional distribution of X given θ , $p(x|\theta)$ (usually specified by model).
- the posterior distribution of θ is simply the conditional distribution of θ given X

$$\pi(\theta|x) = \frac{f(x, \theta)}{p(x)} = \frac{\pi(\theta)p(x|\theta)}{p(x)} \propto \pi(\theta)p(x|\theta)$$

where $p(x)$ is the marginal distribution of X .

• Decision Theory

- **Action space** is the collection of all the actions or decisions, denoted by \mathcal{A} .
- **Loss function** $l(P, a)$ is a function $l : \mathcal{P} \times \mathcal{A} \rightarrow \mathbb{R}^+$, which can be explained as the nonnegative loss incurred by taking action a , while the true distribution is P .
- **Decision rule** δ is a function from the sample space \mathcal{X} to the action space \mathcal{A} .
- **Risk function** is a measure of the performance of the decision rule $\delta(X)$ by averaging loss over the sample space.

$$R(P, \delta) = E_P[l(P, \delta(X))]$$

Particularly, if taking the quadratic loss $l(P, a) = (\nu(P) - a)^2$, then the risk function is called the *Mean Squared Error* (MSE) of $\hat{\nu}$.

- **Bayes risk and Bayes rule:** The *Bayes risk* is defined as

$$r(\delta) = E_{\Pi}[R(\theta, \delta)] = E_{\Pi, P}[l(\theta, \delta(X))]$$

and the *Bayes rule* is the decision rule that minimizes the Bayes risk. $r(\delta^*) = \min_{\delta} r(\delta)$

- **Minimax rule** is the decision rule that minimizes the worst possible risk.

$$\sup_{\theta} R(\theta, \delta^*) = \inf_{\delta} \sup_{\theta} R(\theta, \delta)$$

1.2.1

Consider a parameter space consisting of two points θ_1 and θ_2 , and suppose that for given θ , an experiment leads to a r.v. X whose frequency function $p(x|\theta)$ is given by

$\theta \setminus x$	0	1
θ_1	0.8	0.2
θ_2	0.4	0.6

Let π be the prior frequency function of θ defined by $\pi(\theta_1) = \pi(\theta_2) = \frac{1}{2}$.

- (a) Find the posterior frequency function $\pi(\theta|x)$.
- (b) Suppose X_1, \dots, X_n are independent with frequency function $p(x|\theta)$. Find the posterior $\pi(\theta|x_1, \dots, x_n)$. Observe that it depends only on $\sum_{i=1}^n x_i$.
- (d) Give the values of $P(\theta = \theta_1 | \sum_{i=1}^n X_i = .5n)$ when $n=2$ and 100.
- (e) Give the most probable value $\hat{\theta} = \arg \max_{\theta} \pi(\theta | \sum_{i=1}^n X_i = k)$ for $n=2$ and 100.

1.3.2

In example 1.3.5, the frequency function $p(x, \theta)$ is given by

	$x = 0$	$x = 1$
θ_1	0.3	0.7
θ_2	0.6	0.4

and all possible decision rules are

	δ_1	δ_2	δ_3	δ_4	δ_5	δ_6	δ_7	δ_8	δ_9
$x = 0$	a_1	a_1	a_1	a_2	a_2	a_2	a_3	a_3	a_3
$x = 1$	a_1	a_2	a_3	a_1	a_2	a_3	a_1	a_2	a_3

Suppose a new buyer makes a bid and the loss function is

$\theta \setminus a$	a_1	a_2	a_3
θ_1	0	7	4
θ_2	12	1	6

- (a) Compute and plot the risk points in this case for all possible nonrandomized rules.
- (b) Find the minimax rule among the nonrandomized rules.
- (c) Find the minimax rule among the randomized rules
- (d) Suppose θ has prior $\pi(\theta_1) = \gamma$, $\pi(\theta_2) = 1 - \gamma$. Find the Bayes rule when (i) $\gamma = 0.5$.

1.3.9

Let θ denote the proportion of people working in a company who have a certain characteristic (e.g. being left-handed). It is known that in the state where the company is located, 10% have the characteristic. A person in charge of ordering equipment needs to estimate θ and uses

$$\hat{\theta} = (.2)(.10) + (.8)\hat{p}$$

where $\hat{p} = X/n$ is the proportion with the characteristic in a sample of size n from the company. Find $MSE(\hat{\theta})$ and $MSE(\hat{p})$. If the true θ is θ_0 , for what θ_0 is

$$\frac{MSE(\hat{\theta})}{MSE(\hat{p})} < 1?$$

Give the answer for $n = 25$ and $n = 100$.